



State Observers for Linear Systems with Uncertainty (de Gruyter Expositions in Mathematics)

Sergey K. Korovin, V. V. Fomichev

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This book presents the basic concepts and recent developments of linear control problems with perturbations. The presentation concerns both continuous and discrete dynamical systems. It is self-contained and illustrated by numerous examples. From the contents: Notion of state observers Observability Observers of full-phase vectors for fully determined linear systems Functional observers for fully determined linear systems Asymptotic observers for linear systems with uncertainty Observers for bilinear and discrete systems

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